AMENDMENTS TO THE CLAIMS

This listing of the claims will replace all prior versions and listings of claims in the application:

Listing of Claims:

Claim 1 (currently amended): An interventional catheter assembly comprising:

a. an operating head coupled to a drive shaft and a drive assembly for rotation and having ports communicating with a sealed lumen, wherein the operating head is adjustable between two different operating diameters;

b. a catheter system forming the sealed lumen mounted for axial translation at a proximal end with a control pod and communicating at a distal end with the operating head; and

c. a control pod housing operational components for advancing the catheter system and selectably rotating the operating head, wherein the control pod incorporates a selection switch that allows an operator to select between two different operating head diameters.

Claim 2 (original): An interventional catheter assembly of claim 1, additionally comprising an operating head drive motor coupled to the drive shaft, wherein the drive motor comprises a variable speed drive motor that delivers a constant voltage for any specified rotational output.

Claim 3 (original): An interventional catheter assembly of claim 2, wherein the current delivered to the drive motor is adjusted, under load conditions, if the voltage for any specified rotational output is insufficient to produce the specified rotational output under load conditions.

Claim 4 (original): An interventional catheter assembly of claim 1, additionally comprising an operating head drive motor coupled to the drive shaft, wherein the drive motor employs a cascaded variable regulator voltage source.

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Claim 5 (original): An interventional catheter assembly of claim 1, wherein the control pod

incorporates selectable operator adjustment features allowing an operator to increase and

decrease rotational speed delivered to the drive shaft.

Claim 6 (currently amended): An interventional catheter assembly of claim 1, additionally

comprising:

a. an operating head coupled to a drive shaft and a drive assembly for rotation;

b. a catheter system forming a lumen mounted for axial translation at a proximal end

with a control pod and communicating at a distal end with the operating head;

c. a control pod housing operational components for advancing the catheter system

and selectably rotating the operating head; and

d. a torque selection feature providing preselected torque levels delivered by the

drive assembly to the drive shaft.

Claim 7 (original): An interventional catheter assembly of claim 6, wherein the torque selection

feature incorporates an override setting for each selectable torque level, whereby the drive

assembly is inactivated when a preselected torque level is exceeded.

Claim 8 (original): An interventional catheter assembly of claim 1, wherein the catheter system

has at least one section wherein a coil is provided in proximity to and along a common axis with

a flexible sealed catheter and contacts but is not bonded to the catheter, whereby the flexible

sealed catheter and coil combination provide a kink-free catheter section.

Claim 9 (original): An interventional catheter assembly of claim 1, additionally having an

aspiration motor comprising a multi-lobed vacuum pump that provides a consistent, high level of

aspiration during operation of the interventional catheter assembly.

Claim 10 (original): An interventional catheter assembly of claim 1, additionally having an

aspiration system comprising a plurality of vacuum pumps connected in series.

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Claim 11 (original): An interventional catheter assembly of claim 1, wherein the control pod

houses a drive motor coupled to the drive shaft by means of an arrangement of sliding tubes that

rotate with respect to one another by balls held in slots formed in the tubes.

Claim 12 (original): An interventional catheter assembly of claim 1, wherein the control pod

incorporates a fluid seal assembly providing migration of fluid to a space formed between the

drive shaft and a sealing member to prevent ingress of gas to the catheter system.

Claim 13 (original): An interventional catheter assembly of claim 1, wherein the control pod

incorporates a speed adjustment selection switch controlling rotational speed transmitted to the

drive shaft.

Claims 14 and 15 (cancelled).

Claim 16 (original): An interventional catheter assembly of claim 1, wherein the operating head,

catheter system and control pod are provided as a sterile, disposable kit.

Claim 17 (original): An interventional catheter assembly of claim 16, additionally comprising a

fluid receptacle in fluid communication with the catheter system.

Claim 18 (currently amended): An interventional catheter assembly of claim 1, comprising:

a. an operating head coupled to a drive shaft and a drive assembly for rotation and

having ports communicating with a sealed lumen;

b. a catheter system forming the sealed lumen mounted for axial translation at a

proximal end with a control pod and communicating at a distal end with the operating

head; and

c. a control pod housing operational components for advancing the catheter system

and selectably rotating the operating head,

wherein the control pod houses a drive motor operably coupled to the drive shaft and the

drive motor is coupled to a sliding actuator mounted on the catheter system distally to the

control pod such that the drive motor is actuated when the sliding actuator grips the

catheter system and advances it.

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Claim 19 (original): An interventional catheter assembly of claim 1, wherein the control pod

incorporates a guidewire brake operable to clamp a guidewire in a stationary position when

engaged and to allow translation of the guidewire through the brake when released.

Claim 20 (original): An interventional catheter assembly of claim 19, additionally comprising a

guidewire brake control system interrupt that prevents the drive system from being actuated when

the guidewire brake is in a release position.

Claim 21 (original): An interventional catheter assembly of claim 19, additionally comprising a

guidewire brake selectable interrupt override control that, when actuated, permits an operator to

selectably permit operation of the drive system when the guidewire brake is in a release position.

Claim 22 (cancelled).

Claim 23 (original): An interventional catheter assembly of claim 1, additionally comprising an

extendable, telescoping guidewire support mounted in the control pod.

Claim 24 (original): An interventional catheter assembly of claim 1, additionally comprising a

console unit incorporating system control and display features and a motor providing vacuum for

aspiration to the catheter assembly.

Claim 25 (original): An interventional catheter assembly of claim 24, wherein the motor

comprises a multi-lobed vacuum pump that provides consistent, high levels of aspiration during

operation of the interventional catheter assembly.

Claim 26 (original): An interventional catheter assembly of claim 24, wherein the motor

comprises a plurality of vacuum pumps connected in series to provide constant, high levels of

aspiration during operation of the interventional catheter assembly.

Claim 27 (original): An interventional catheter assembly of claim 24, wherein the console unit is

in electrical communication with the control pod and provides power to the drive system.

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Claim 28 (original): An interventional catheter assembly of claim 24, wherein the console unit

displays output operational information including at least three of operating head rotation rate,

operating head advance rate, aspiration rate, elapsed time of operation, aspiration volume, and

fluid flow rate at the target site.

Claim 29 (new): An interventional catheter assembly of claim 1, wherein the selection switch

changes the direction of rotational output of the drive system.

Claim 30 (new): An interventional catheter assembly of claim 6, additionally comprising an

operating head drive motor coupled to the drive shaft, wherein the drive motor comprises a

variable speed drive motor that delivers a constant voltage for any specified rotational output.

Claim 31 (new): An interventional catheter assembly of claim 6, additionally comprising an

operating head drive motor coupled to the drive shaft, wherein the drive motor employs a

cascaded variable regulator voltage source.

Claim 32 (new): An interventional catheter assembly of claim 6, wherein the control pod

incorporates selectable operator adjustment features allowing an operator to increase and

decrease rotational speed delivered to the drive shaft.

Claim 33 (new): An interventional catheter assembly of claim 6, wherein the catheter system has

at least one section wherein a coil is provided in proximity to and along a common axis with a

flexible sealed catheter and contacts but is not bonded to the catheter, whereby the flexible sealed

catheter and coil combination provide a kink-free catheter section.

Claim 34 (new): An interventional catheter assembly of claim 6, additionally comprising an

aspiration system comprising a multi-lobed vacuum pump that provides a consistent, high level

of aspiration during operation of the interventional catheter assembly.

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Claim 35 (new): An interventional catheter assembly of claim 6, additionally comprising an

aspiration system comprising a plurality of vacuum pumps connected in series.

Claim 36 (new): An interventional catheter assembly of claim 6, wherein the control pod houses

a drive motor coupled to the drive shaft by means of an arrangement of sliding tubes that rotate

with respect to one another by balls held in slots formed in the tubes.

Claim 37 (new): An interventional catheter assembly of claim 6, wherein the control pod

incorporates a fluid seal assembly providing migration of fluid to a space formed between the

drive shaft and a sealing member to prevent ingress of gas to the catheter system.

Claim 38 (new): An interventional catheter assembly of claim 6, wherein the operating head,

catheter system and control pod are provided as a sterile, disposable kit.

Claim 39 (new): An interventional catheter assembly of claim 6, wherein the control pod

incorporates a guidewire brake operable to clamp a guidewire in a stationary position when

engaged and to allow translation of the guidewire through the brake when released.

Claim 40 (new): An interventional catheter assembly of claim 6, additionally comprising a

console unit incorporating system control and display features and a motor providing vacuum for

aspiration to the catheter assembly.

Claim 41 (new): An interventional catheter assembly of claim 40, wherein the motor comprises

a multi-lobed vacuum pump that provides consistent, high levels of aspiration during operation

of the interventional catheter assembly.

Claim 42 (new): An interventional catheter assembly of claim 40, wherein the console unit is in

electrical communication with the control pod and provides power to the drive system.

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Claim 43 (new): An interventional catheter assembly of claim 18, additionally comprising an

operating head drive motor coupled to the drive shaft, wherein the drive motor comprises a

variable speed drive motor that delivers a constant voltage for any specified rotational output.

Claim 44 (new): An interventional catheter assembly of claim 18, additionally comprising an

operating head drive motor coupled to the drive shaft, wherein the drive motor employs a

cascaded variable regulator voltage source.

Claim 45 (new): An interventional catheter assembly of claim 18, wherein the control pod

incorporates selectable operator adjustment features allowing an operator to increase and

decrease rotational speed delivered to the drive shaft.

Claim 46 (new): An interventional catheter assembly of claim 18, wherein the catheter system

has at least one section wherein a coil is provided in proximity to and along a common axis with

a flexible sealed catheter and contacts but is not bonded to the catheter, whereby the flexible

sealed catheter and coil combination provide a kink-free catheter section.

Claim 47 (new): An interventional catheter assembly of claim 18, additionally comprising an

aspiration system comprising a multi-lobed vacuum pump that provides a consistent, high level

of aspiration during operation of the interventional catheter assembly.

Claim 48 (new): An interventional catheter assembly of claim 18, additionally having an

aspiration system comprising a plurality of vacuum pumps connected in series.

Claim 49 (new): An interventional catheter assembly of claim 18, wherein the control pod

houses a drive motor coupled to the drive shaft by means of an arrangement of sliding tubes that

rotate with respect to one another by balls held in slots formed in the tubes.

Claim 50 (new): An interventional catheter assembly of claim 18, wherein the control pod

incorporates a fluid seal assembly providing migration of fluid to a space formed between the

drive shaft and a sealing member to prevent ingress of gas to the catheter system.

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Claim 51 (new): An interventional catheter assembly of claim 18, wherein the operating head,

catheter system and control pod are provided as a sterile, disposable kit.

Claim 52 (new): An interventional catheter assembly of claim 18, wherein the control pod

incorporates a guidewire brake operable to clamp a guidewire in a stationary position when

engaged and to allow translation of the guidewire through the brake when released.

Claim 53 (new): An interventional catheter assembly of claim 18, additionally comprising a

console unit incorporating system control and display features, and a motor providing vacuum for

aspiration to the catheter assembly.

Claim 54 (new): An interventional catheter assembly of claim 53, wherein the motor comprises

a multi-lobed vacuum pump that provides consistent, high levels of aspiration during operation

of the interventional catheter assembly.

Claim 55 (new): An interventional catheter assembly of claim 53, wherein the console unit is in

electrical communication with the control pod and provides power to the drive system.

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